

Amendments to the Abstract:

The Abstract has been amended as follows. A revised Abstract, including the changes reflected below, is attached.

A transmission joint for transmitting drive between a first shaft and a second shaft ~~(2, 3)~~ ~~comprises~~-includes a first joint element and a second joint element ~~(4, 5)~~ which can be mutually coupled for the transmission of the drive between the shafts, each element ~~(4, 5)~~ being rotatable about a respective first or second axis of rotation ~~(X1, X2)~~. The first joint element ~~(4)~~ ~~comprises~~-includes an approximately spheroidal body ~~(6)~~ formed by a plurality of adjacent segment-like portions ~~(6a)~~ having curved external profile surfaces and defining, transverse the first axis ~~(X1)~~, cross-sections of the body with polygonal outlines. The spheroidal body ~~(6)~~ can engage a blind axial cavity ~~(10)~~ of the second joint element ~~(5)~~ having a cross-section, transverse the second axis ~~(X2)~~, with a polygonal outline corresponding to the profile of the body ~~(6)~~ and of dimensions such that the first joint element ~~(4)~~ is housed in the second joint element ~~(5)~~ with mutual torsional coupling and a capability for relative inclination of the axes of the joint elements for the transmission of drive between the ~~said~~ shafts ~~(2, 3)~~ with non-aligned axes. ~~Means are provided on~~ ~~the~~ The joint elements ~~(4, 5)~~ for limiting the relative angular inclination of the axes ~~(X1, X2)~~ of rotation of the joint elements, in order consequently to permit the correct transmission of drive between inclined shafts ~~(2, 3)~~, up to a preselected maximum angular inclination ~~(A)~~.